

SPL170 Terminal GUI Viewer User Manual



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1 Brief Introduction

1.1 System Introduction

SPL170 Terminal is a GUI software used by SPL170, which is mainly used for real-time display, recording the data. It's compiled on the Windows 10 platform, and it's recommended to install and use it on Windows 10 and above systems.

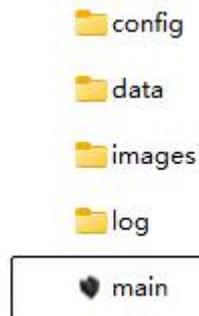
1.2 Preparation before testing

			
SPL170	12V power supply	RS232-USB converter	PC with Windows 10



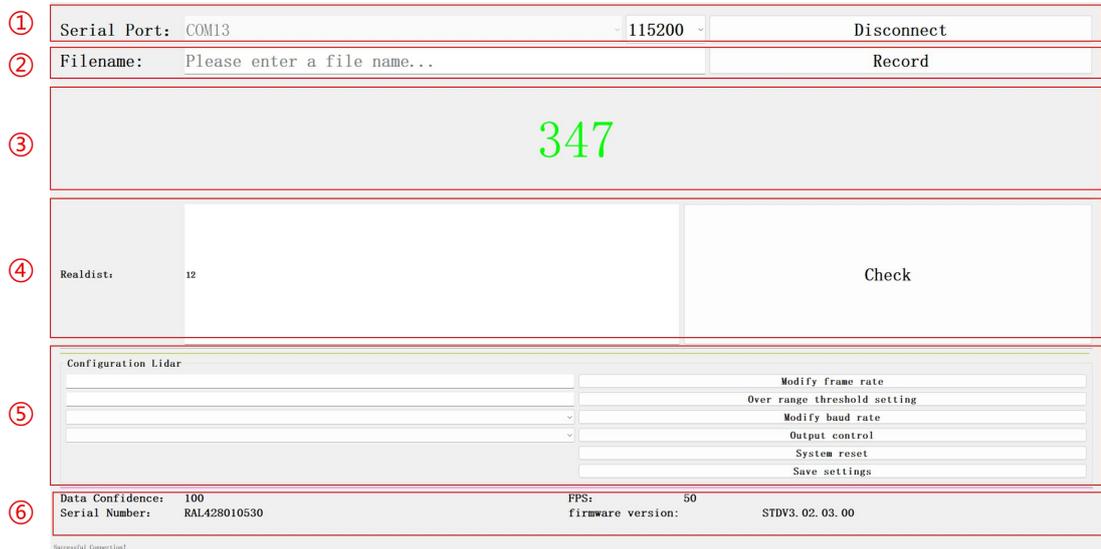
2 File Structure

Terminal file structure as shown in the figure, double-click "main.exe" to open the GUI program.



3 Interface Introduction

The main interface is shown in the following figure:



1. LiDAR connection
2. Data recording
3. Real-time data display
4. Data verification
5. LiDAR configuration
6. LiDAR status

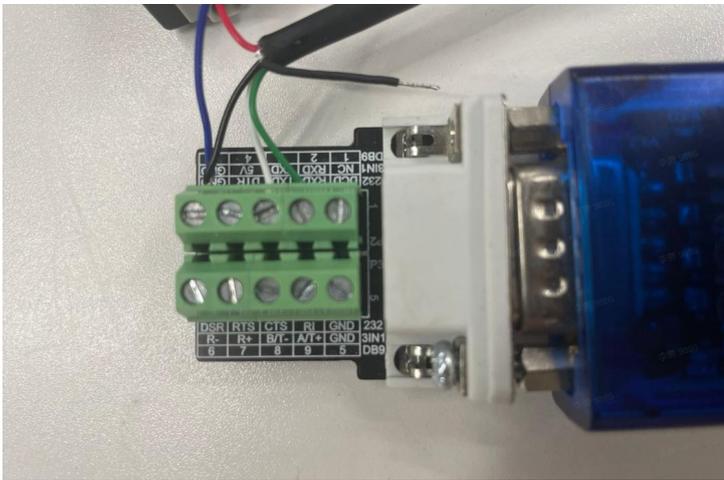


4 Operating Instruction

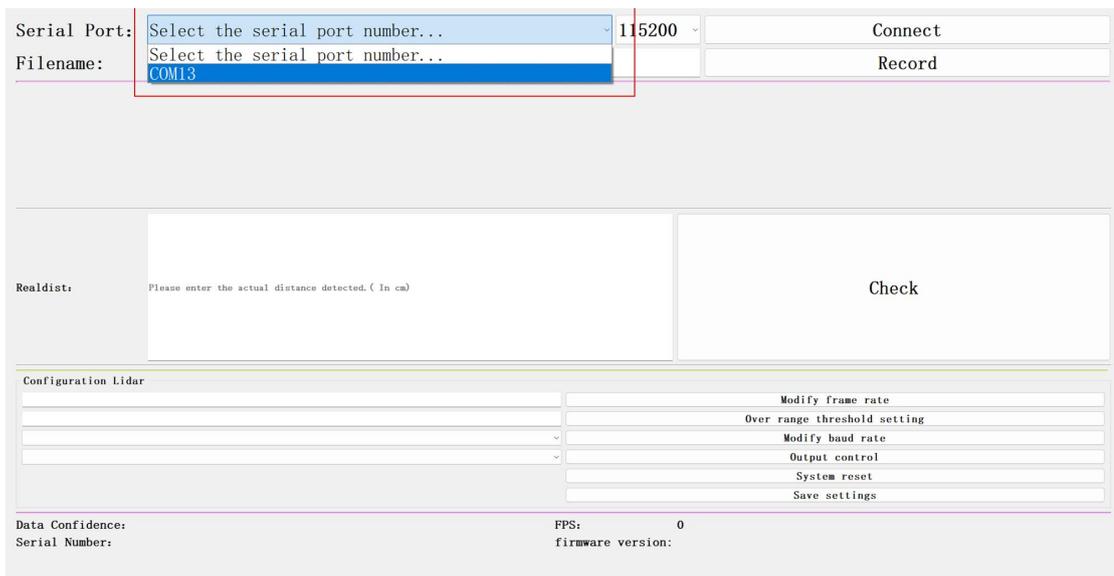
4.1 Connection

Connect SPL170 to PC via the RS232-USB converter:

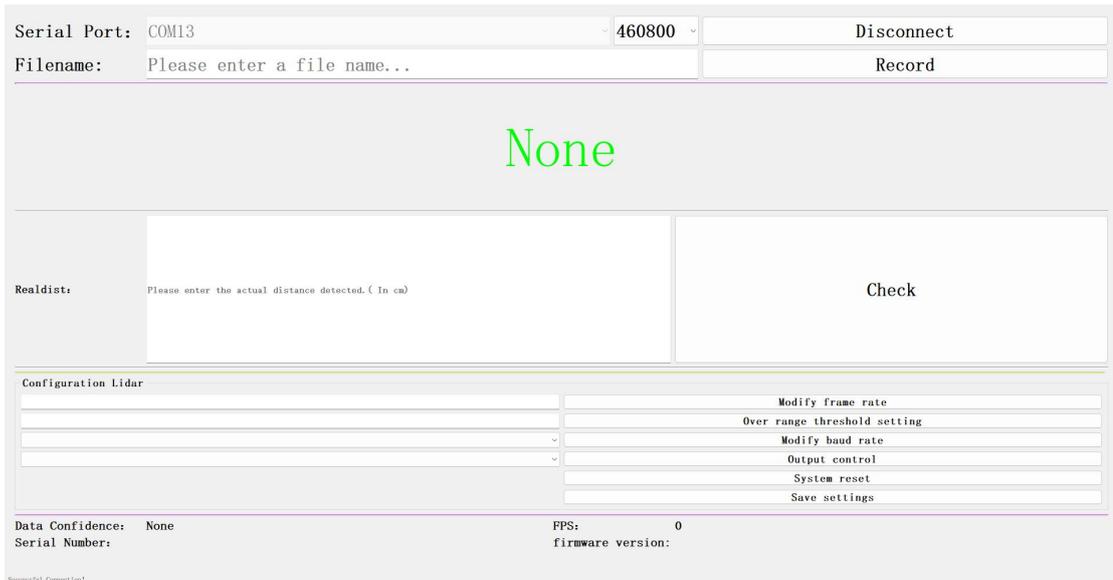
1. As wire sequence defined, connect LiDAR's RS232-RX(*White cable*) to TXD of RS232-USB converter, then connect RS232-TX(*Green cable*) to RXD.
2. Connect the GND and VCC of power adapter to RS232-USB converter.(Note: connect GND of LiDAR to converter before powering on.)



3. Connect USB of the converter to PC.
Open the GUI after successful connection, choose the serial port of the converter, then click "Connect", there will be data output in the GUI (Default baud rate: 115200) .



Note: If the baud rate is wrong, there will be "None" shown in the GUI.



4.2 Real-time data display



The distance will be shown as above after successful connection, the unit is CM.

4.3 Data Recording

Input the file name in "Filename", then click "Record", the GUI will save data of LiDAR automatically.

Click "Recording" to finish recording, the data file will pop up automatically. The file format is ".txt".



Serial Port: COM13 115200 Disconnect

Filename: HelloWord Record

392

Realdist: Please enter the actual distance detected. (In cm) Check

Configuration Lidar

<input type="text"/>	<input type="text"/> Modify frame rate
<input type="text"/>	<input type="text"/> Over range threshold setting
<input type="text"/>	<input type="text"/> Modify baud rate
<input type="text"/>	<input type="text"/> Output control
<input type="text"/>	<input type="text"/> System reset
<input type="text"/>	<input type="text"/> Save settings

Data Confidence: 100 FPS: 50
 Serial Number: RAL428010530 firmware version: STDV3. 02. 03. 00

Successful Connection!



4.4 Data Verification

If you want to check the error between data and real distance, enter the real distance value next to the "Realdist:", then click "Check" to record data, when you click "Checking", the GUI will stop recording data and tell the error results(Pass or Failed). For example, the data of LiDAR is 387cm, if the real distance is 386cm, the GUI will output "Pass", otherwise, it will output "Failed".

Serial Port: COM13 115200 Disconnect

Filename: Please enter a file name... Record

387

Realdist: Please enter the actual distance detected. (In cm) Check

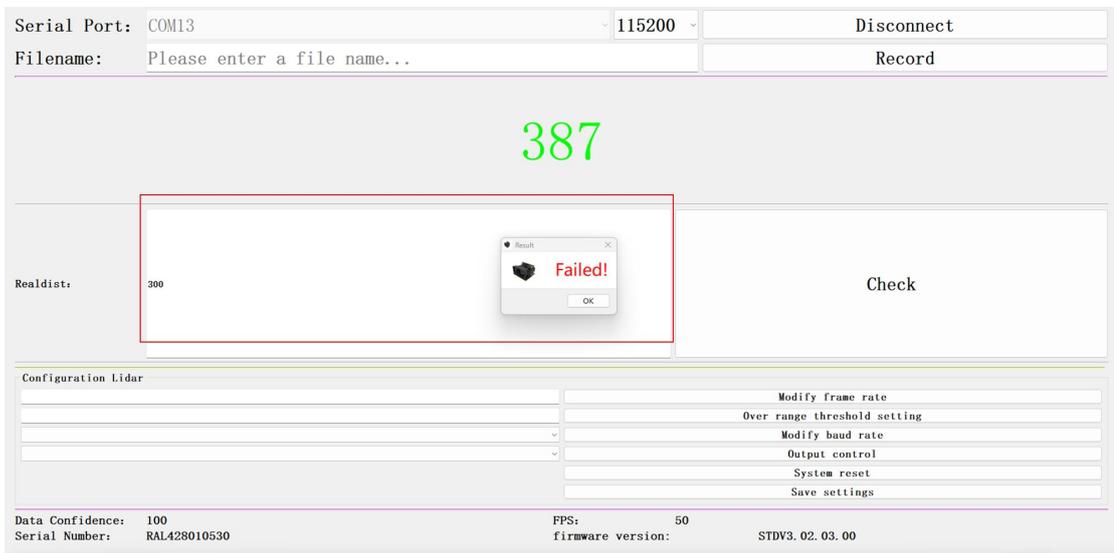
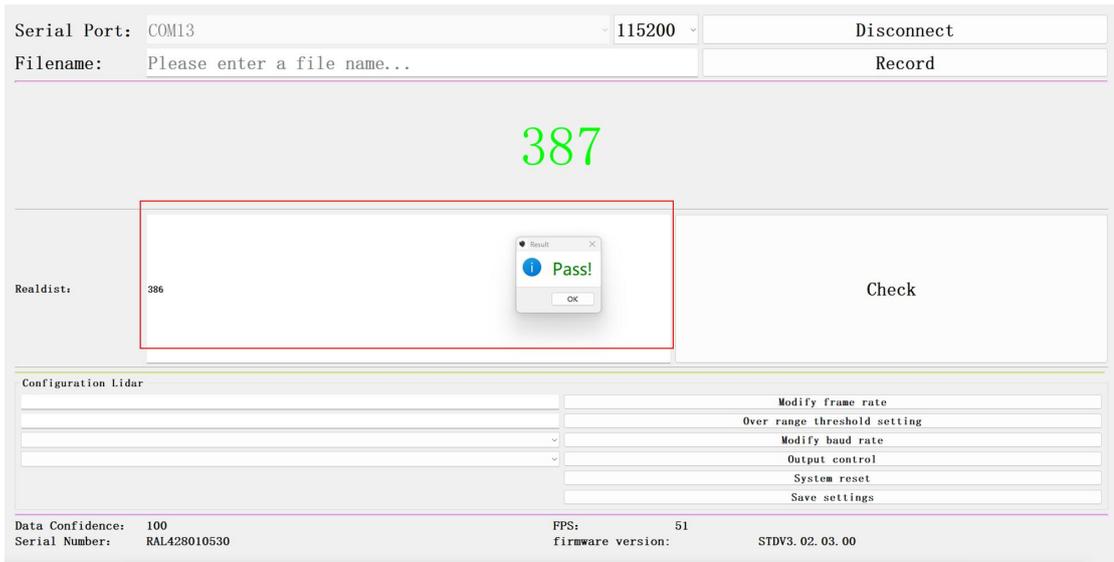
Configuration Lidar

<input type="text"/>	<input type="text"/> Modify frame rate
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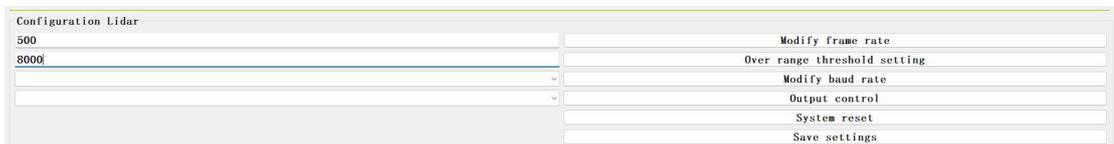
Data Confidence: 100 FPS: 50
 Serial Number: RAL428010530 firmware version: STDV3. 02. 03. 00

Successful Connection!





4.5 LiDAR Configuration



- The GUI supports modifying the baud rate, frame rate, system reset, save configuration, over range threshold.
- Default frame rate value is 50Hz.
- Default over range threshold value is 10000cm, the unit is CM.



4.6 LiDAR Status

```
Data Confidence: 100          FPS: 49
Serial Number:   RAL428010530  firmware version: STDV3.02.03.00
```

Successful Connection!

- The GUI will display the confidence level, frame rate, serial number, and software version number.
- The information will show automatically after connecting serial port.



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